

CATS Sine Control





Analog quality sine signal generation

- Multi-channel digital tracking filters with variable fixed and proportional bandwidths
- Digital re-sampling provides true proportional bandwidth tracking filters
- Sweep range from 0.1 to 10,000 Hz
- Optional resonance search and phasetracked dwell
- Frequency Response Function (FRF) measurements for all active channels
- Independent limit profiles for each active measurement channel

Sine testing can be done two ways:

- Overall test level control, where we do not care about what frequency causes the response energy.
- 2. Fundamental Control, which requires Tracking Filters. See Figure 2 below

Nearly all tests presume Tracking Filters are being employed. PUMA provides True analog quality tracking filters created in DSP with the same Sine-Co-Sine Heterodyne method SD patented in 1961, If you must test to MilStd expectations, you must use tracking filters. FFT based processes DO NOT yield the same accuracy that Digital Tracking Filters offer.

Signal Generation hardware matters. PUMA generates harmonic free analog quality Sine signals that permit remarkable resonance control and accuracy.

NOT generating Harmonic content, means the power amplifier WON'T receive high frequency energy which it CANNOT reproduce, thereby removing another worry from the Test Professional's mind.



CATS Computer Aided Test Suite Graphics so POWERFUL, the user interface can be simple



CATS Sine

Technical Specifications Loop check max. drive User-selectable, 0 to 5,000 mV RMS

Continuous automatic detection

Control Methods	
Control loop	True analog-quality sine sweep with a double precision integrated phase algorithm for low distortion
Control Performance	
Dynamic range	Greater than 80 dB with 0.05 dB level step control over the full range
Output signal	Analog-quality digital sine generation, using a double precision integrated phase algorithm for low distortion
Level accuracy	Control to within ± 1 dB at a sweep rate of 1 oct/min through a 600 Hz resonance of a linear system with a Q of 70 with an internal 20% proportional tracking filter Sweep frequency resolution±0.5% of the drive frequency
Loop time	Less than 5 msec for single channel control
Compression rate	Up to 3,500 dB/sec with unconditionally stable feedback control loop
Harmonic distortion	< -75 dB at full output
Reference Profile	
Definition	Up to 500 frequency segments
Segment types	Constant displacement, velocity, acceleration, and straight line acceleration (linear or logarithmic)
Crossover frequencies	Automatically calculated to avoid segment boundary discontinuities
Alarm and abort limits	Independent positive and negative alarm and abort margins
Sweep range	User-defined sweep range from 1 to 5000 Hz; and 0.01 to 10000 Hz (Premier) optional
Sweep resolution	User-defined resolution of 450 to 800 points per sweep; 450 to 2400 points per sweep (Premier) optional
Spectrum dynamic limits	Acceleration range, maximum or minimum acceleration, maximum velocity and maximum displacement
Limit Profiles (optional)	alopidosition
Definition	Up to 500 frequency segments
Segment types	Constant displacement, velocity, acceleration, and straight line acceleration (linear or logarithmic)
Crossover frequencies	Automatically calculated to avoid segment boundary discontinuities
Number	Up to the number of active channels minus one (Premier)
Control Parameters	
Mode of operation	Manual, automatic
Test duration	Maximum 99,999 sweeps or 9999:59:59 (hhhh:mm:ss); unlimited test
Measurement processing	RMS, or tracking filter processing for all channels in parallel; processing type individually selectable for each channel
Tracking filter types	Proportional to drive frequency, 1 to 200% and fixed bandwidth, 1 Hz to 1,000Hz
Transducer types	Control based on acceleration, velocity, displacement (transducer with programmable transition frequency band)
Number of control channels Multi-channel control strategy	1 to all available channels, max 16 RMS, arithmetic average, min, max
Abort channels Compression	Abort test when user-defined level exceeded 5% to 100%
Units	m/s² - m/s - mm; q – in/sec - in; q - m/s – mm
Box Tolerance Enable Startup/Shutdown Rate	Alarm & Abort width set 0 to 100% 1 to 99 dB/sec
Sweep Parameters	Lincor logorithmic
Sweep mode	Linear, logarithmic
Sweep duration	User-defined, maximum 999:59:59 (hhh:mm:ss)
ivurnber of sweeps	
Sweep rate-linear	0.00003 to 300 Hz/sec (0.0018 to 18,000Hz/min)
Sweep rate-logarithmic	
Initial sweep direction	Up, down
Satety Features	
Snaker limits	Pretest verification that spectrum dynamic limits are within shaker operational limits (acceleration, velocity

displacement and voltage)

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Dwell level type Data Storage Setup options Playback Documentation Test summary Run message log Safety Features Shaker limits Loop check max. drive Control signal loss Manual abort Maximum drive signal Startup/shutdown rates

Control signal loss

Test Automation Test scheduling

Sweep rate table

Schedule cycles

Print Automation

Engineering Units

Channel Setup Channel type

Channel loop check

Transducer Database

Display functions

Scaling of display Real-time/stored data

Passive Sine Analysis

Resonance Search & Dwell (optional) Dwell modes

Search parameters Q Search

Search Channel

Resonance calculation Dwell table parameters

Smoothing

Cursors

On-Line Test Analysis

Channel label

Sensitivity

Base Engineering Units

Calculations

Compression table

Maximum drive signal

Startup/shutdown rates

Manual abort

Graphical and keyboard abort buttons 0.0001 to 12 V peak Independently selectable, 1 to 99 dB/sec User-defined sequence of up to 500 independent tests run automatically Up to 50 sweep rate vs. frequency segments Up to 50 compression speed vs. frequency segments 1 to 100 Ability to create reports Automatically with Customized displays Label(EU), Conversion(EU/Transducer Units) Integrated (Label and Scale Factor), Double Integrated(Label and Scale Factor), Differentiated (Label and Scale Factor), Double Differentiated (Label and Scale Factor) Control, measurement, reference, limit, abort, inactive 0.001 to 999,999 mV/g or mV/(m/s2) mm; EU for Measurement Channels Enabled, disabled Up to 20 characters for each channel Transducer serial number Up to 10 characters for each channel Table Driven Archival Database Control, drive, measurement channel 1 to 32, frequency response function (magnitude/phase or real/imaginary X and Y value readout, peak search, trace tagging, multi-window looked positioning Log/linear, auto-scaled/fixed Simultaneous display and overlay of real-time data and any stored data Same capability as test operations w/o output generation Fixed frequency, phase tracked(auto/manual), Continuous (w/reset option) Max no. of resonances, hysteresis, minimum Q value Peak Ratio or -3dB points Low, Medium, High Any active channel Any active channel Phase Reference Channel Resonance frequency, Q, phase, level Duration, start frequency, dwell frequency, end frequency, dwell level and phase, alarm limit, abort limit Acceleration, velocity, displacement

> Sweep Increment, first sweep, last sweep Scan through the entire test data file, with adjustable delay and Tagging

Fully documented post-test summary, easily printed or incorporated into any document using standard word processing software Text file records all system status messages displayed during test run

Pretest verification that spectrum dynamic limits are within shaker operational limits (acceleration, velocity, displacement and voltage) User-selectable, 0 to 5,000 mV RMS Continuous automatic detection Graphical and keyboard abort buttons 0.0001 to 12 V peak Independently selectable, 1 to 99 dB/sec

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